

Predicting Dynamical Evolution of Human Activities from a Single Image

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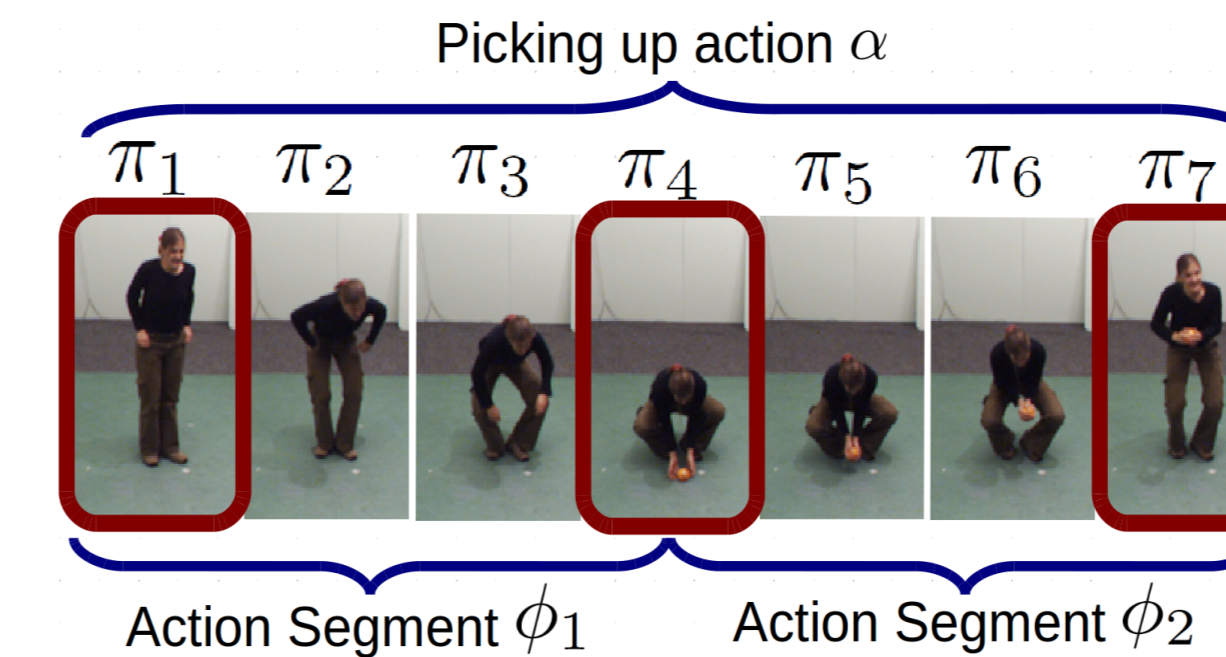
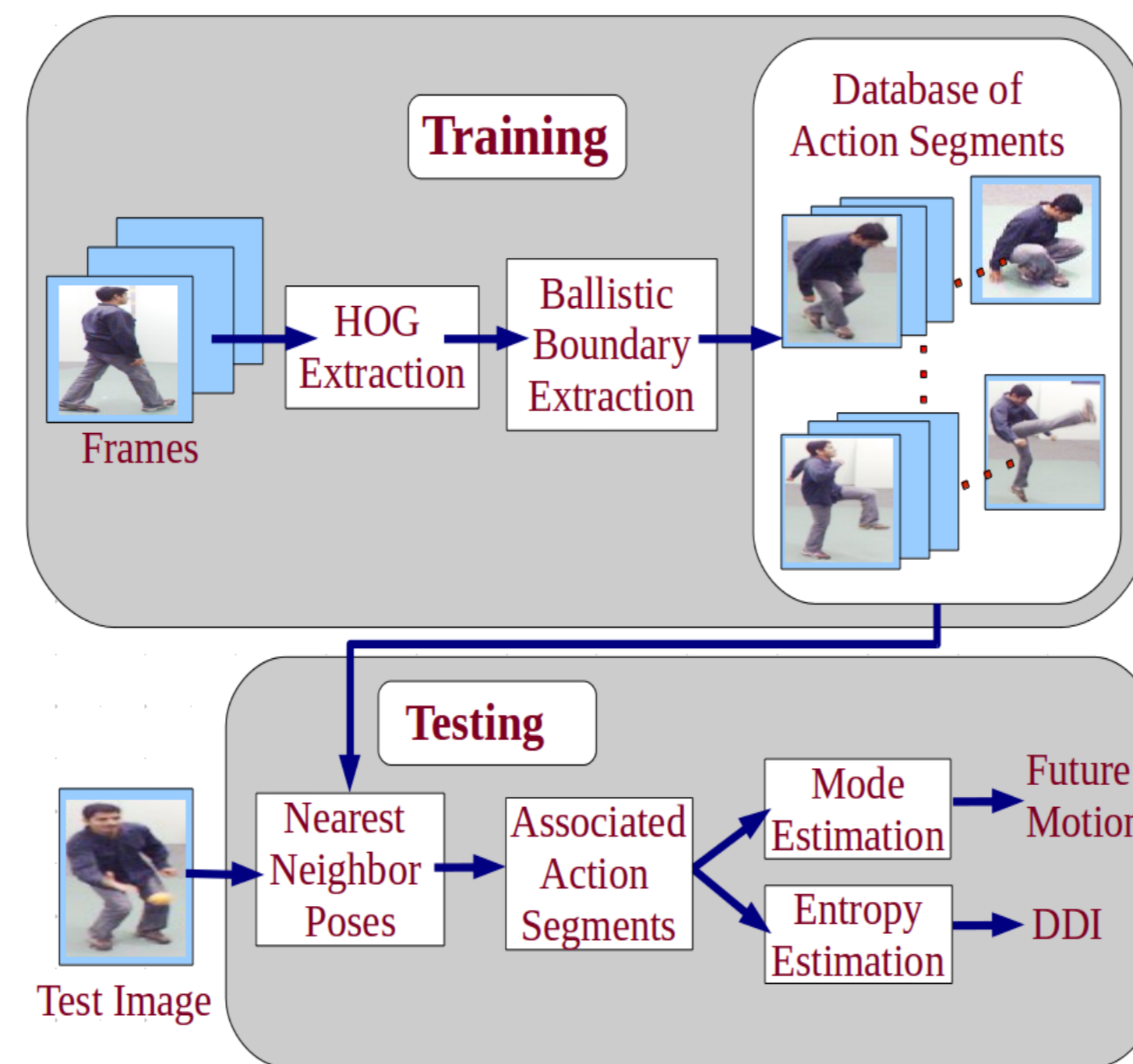
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Motion Inference from Human Pose

- Posture of a human body is an important indicator of ensuing motion e.g. the experiments of Hirai and Hiraki [1]
- Given a single pose, we use statistical inference on the Grassmannian to predict the future motion of a human computationally
- We quantify the extent to which future motion is constrained by a given pose
- We apply this approach to a variety of vision problems like human motion prediction and activity recognition

Computational Approach for Predicting Human Activity from a Single Image



- We define degree of dynamic information (DDI) present in a pose:

$$\mathcal{H}(\phi|\pi) = - \int_{\phi \in \Phi} \mathcal{P}(\phi|\pi) \log(\mathcal{P}(\phi|\pi)) d\phi$$

$$\text{DDI}(\pi) = \exp[-\mathcal{H}(\phi|\pi)]$$

Estimating the conditional distribution

- Modeling action segments using LDS

$$z_\phi(t+1) = A_\phi z_\phi(t) + v_\phi(t), v_\phi(t) \sim N(0, \Xi)$$

$$y_\phi(t) = C_\phi z_\phi(t) + w_\phi(t), w_\phi(t) \sim N(0, \Theta)$$

$$\Omega_\phi^\top = [C_\phi^\top, (C_\phi A_\phi)^\top, \dots, (C_\phi A_\phi^{m-1})^\top, \dots]$$

$$\zeta^2(\Omega_i, \Omega_j) = p - \text{tr}(\Omega_j^\top \Omega_i \Omega_i^\top \Omega_j)$$
- Density estimation on the Grassmannian [3]

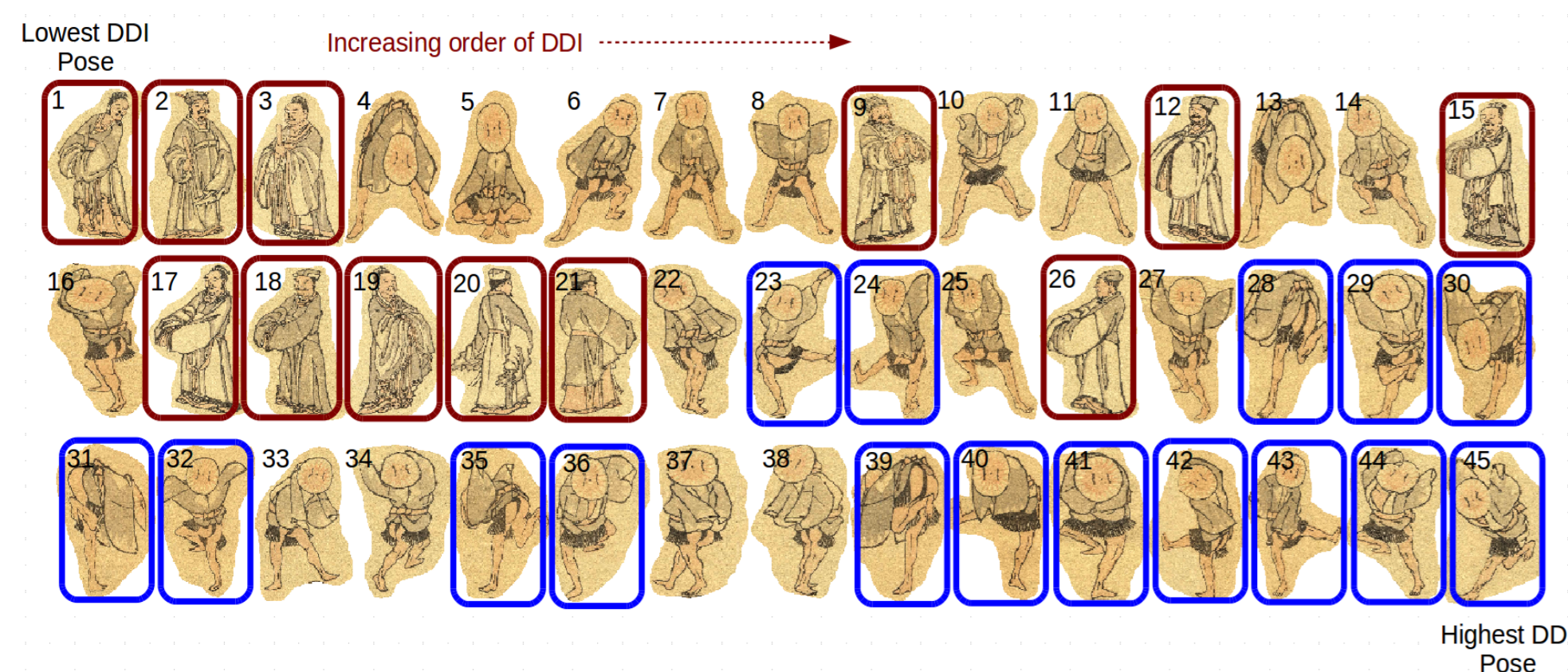
$$\hat{\mathcal{P}}(\phi|\pi_s) = c_1 \sum_{\phi_i \in \mathcal{N}_{\phi}(\pi_s)} \Psi(M^{-\frac{1}{2}}(I_d - \Omega_i^\top \Omega \Omega^\top \Omega_i)M^{-\frac{1}{2}})$$
- Statistical inference on the estimated density

$$\hat{\phi}(\pi_s) = \arg \max_{\phi_i \in \mathcal{N}_{\phi}(\pi_s)} \hat{\mathcal{P}}(\phi_i|\pi_s)$$

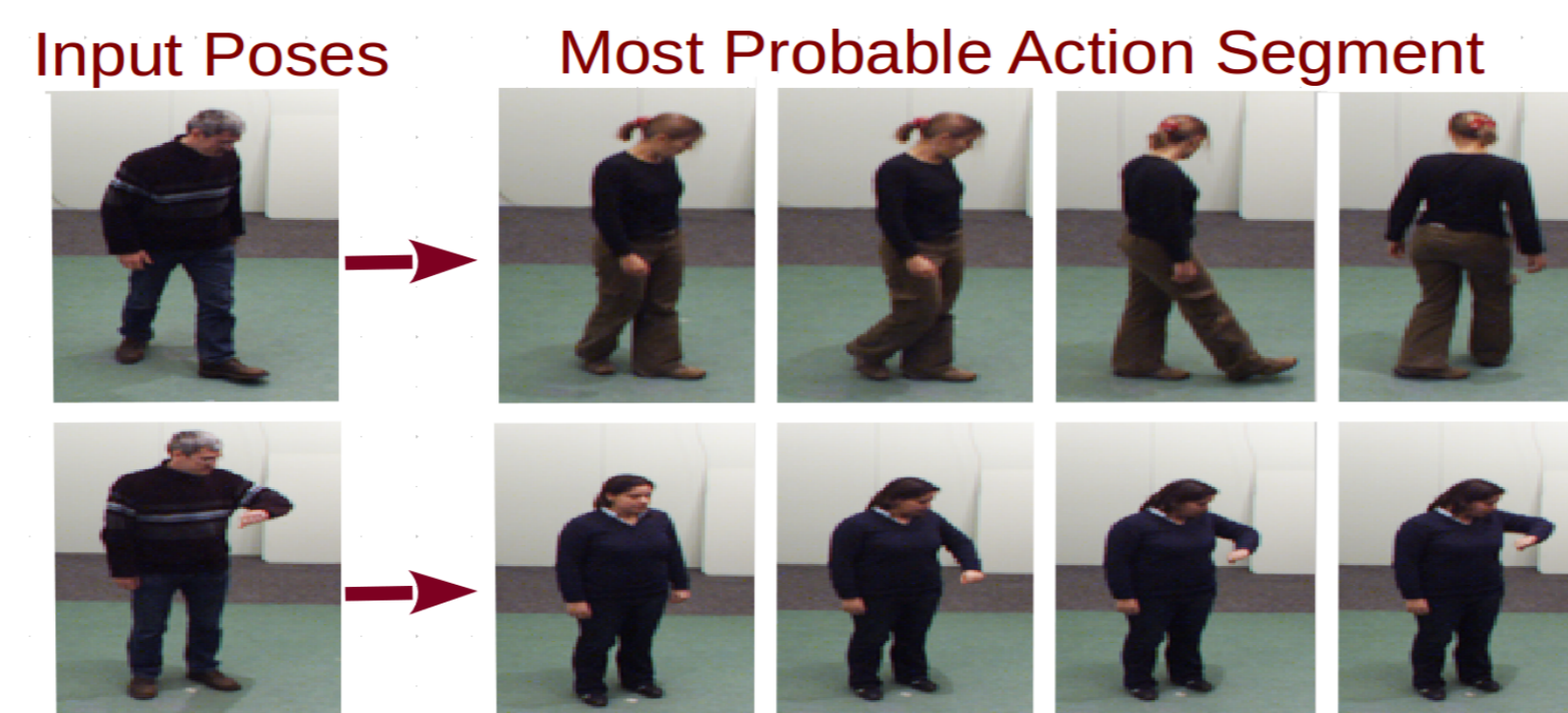
Applications and Experimental Results

1. Perceptual Evaluation on Manga Images

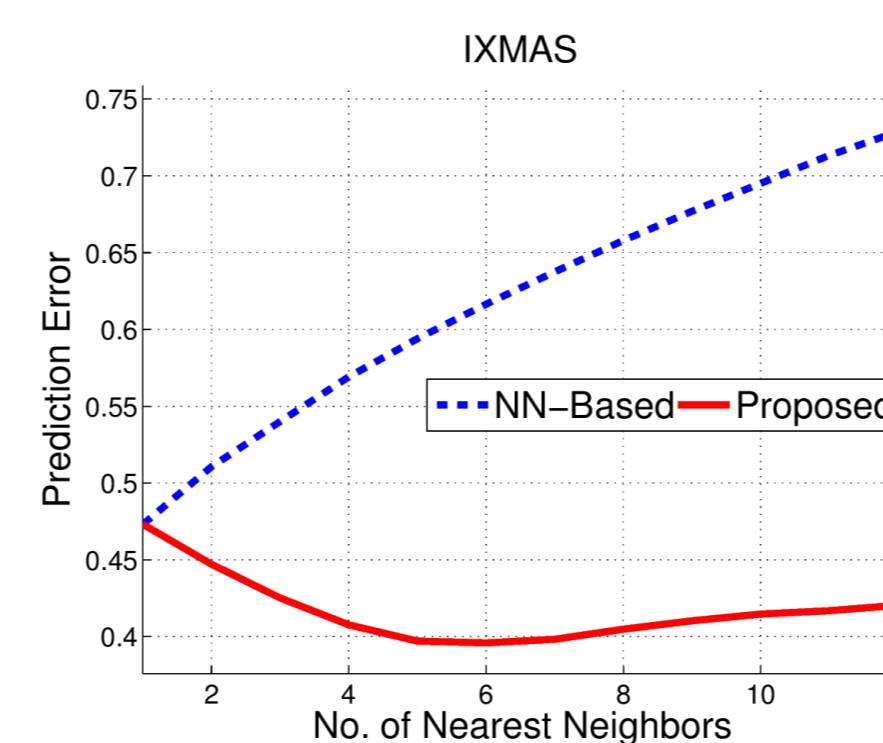
- We estimate the amount of motion information in the Hokusai Manga image database
- Osaka et al. [4] showed that the dancer images activated the motion sensitive regions of the visual cortex, while the priest images did not
- Our DDI metric shows very similar trends



2. Human Motion Prediction



- We use IXMAS dataset to predict motion given a single pose
- We used first nine subjects in the first view as training data and predicted future motion for each pose of last subject.



3. Semi-supervised Single-Image Action Recognition

- We evaluate the label propagation technique for semi-supervised activity recognition
- We considered nine actions of UCF Sports Activity dataset, using 2 subjects for training, 2 for testing and 8 as unlabeled data

